 STUDENT ID NO								

MULTIMEDIA UNIVERSITY

FINAL EXAMINATION

TRIMESTER 2, 2017/2018

ERT 3056 – INTRODUCTION TO CIM

5 MARCH 2018 2.30 p.m. – 4.30 p.m. (2 Hours)

INSTRUCTION TO STUDENTS

- 1. This Question paper consists of 4 pages including cover page with 4 Questions only.
- 2. Attempt all **FOUR** questions. All questions carry equal marks and the distribution of the marks for each question is given.
- 3. Please write all your answers in the Answer Booklet provided.

Question 1

a) Give comparison between Boundary Representation (B-rep) and Constructive Solid Geometry (CSG) in terms of implementation.

[10 marks]

b) Compared to the CSG representation, which uses only primitive objects and Boolean operations to combine them, B-rep is more flexible and has a much richer operation set. Give another FIVE reasons, why B-rep is commonly used in CAD software?

[5 marks]

c) A surface model represents the skin of an object, while solid modeling is a complete geometric data representation of an object is one that enables points in space to be classified relative to the object. Distinguish the **FIVE** advantages each of implementing solid modeling and surface modeling.

[10 marks]

Question 2

a) What are the **THREE** types of raw materials used in rapid prototyping fabrication?

[3 marks]

b) Besides the raw material, what other process feature distinguishes the rapid prototyping technologies?

[4 marks]

c) Distinguish how Fused Deposition Model (FDM) and Stereo Lithography (SLA) technologies work.

[18 marks]

Continued...

Question 3

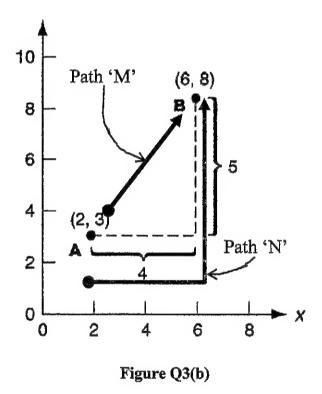
a) By means of a neat sketch, differentiate the **THREE** types of work-holding methods that are used in CNC machining centres.

(Note: Please write the working principals based on your sketch provided)

[12 marks]

b) By analyzing Figure Q3(b), state the preferred 'Positioning System' in the real time CNC industry by selecting path 'M' or 'N'. Provide **TWO** reasons to support your answer.

[4 marks]



3/4

Continued...

- c) Find the correct CNC coding's for the following operations:
 - i) Linear Interpolation/Slow traverse
 - ii) Circular Interpolation: Clockwise
 - iii) Circular Interpolation: Counter clockwise
 - iv) Program stop
 - v) Spindle stop
 - vi) Tool change
 - vii) Coolant on
 - viii) Program stop, reset to start
 - ix) Subprogram call

[9 marks]

Question 4

a) Robots are heavily used in the manufacturing sectors for material handling.
State the main components of a robot and explain your answer.

[12 marks]

b) Identify SIX advantages of Automatic Guided Vehicles (AGV).

[6 marks]

c) Identify **SEVEN** benefits in Computer Integrated Manufacturing (CIM) and explain them briefly.

[7 marks]

End of Paper